

Analysis of Coalitional Game Methodology for Packet Delivery in Mobile Adhoc Network

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ABSTRACT: *We suggest an solution based on a coalition formation among mobile nodes to cooperatively deliver packets among those mobile nodes inside the comparable coalition. To find out the payoff of every cellular node, a non-stop time Markov chain model is formulated and the anticipated value and packet sending rescheduling are obtained whilst the mobile node is in a coalition. Because each the expected fee and packet delivery postpone depending on the possibility that every cellular node will useful resource other mobile nodes inside the same coalition to forward packets to the destination mobile node in the equal coalition, a bargaining model sport is used to discover the fine supporting possibilities. Behind the payoff of every mobile node is acquired, we find out the resolutions of the coalitional game that are the constant coalitions. A distributed algorithm is reachable to gain the constant coalitions and a Markov-chain-based the analysis is used to estimate the steady coalitional systems obtained from the distributed algorithm.*

KEYWORDS-

I. INTRODUCTION

Ad hoc networks are infrastructure-less multi-hop wireless networks where each node participates in routing by forwarding data for other nodes. Those networks are self-organizing and are used when usual infrastructure is not available or not suitable, e.g., in wireless sensor networks (WSN), vehicular networks (VANET), public protection and disaster relief (PPDR), or military systems. In order to implement practical large ad hoc networks, gathering nodes in clusters (called clustering) was first proposed in the early 80s [1] for HF packet radio networks, and has so far triggered a lot of work in the literature. For instance, it was proposed in the context of VANETs [2] and cognitive radio networks [3].

Most existing works about ad hoc network clustering have focused on unstructured networks. For example in [4] the authors propose the lowest identifier (LID) and highest degree clustering (HC) algorithms where nodes with the lowest identifier, respectively the largest degree within their neighborhood, become cluster head (CH). To form the clusters, non-CH nodes affiliate to their neighbor CH with the lowest identifier, respectively the largest degree. The stability of the clusters formed with LID or HC, has been improved in [5] with the least cluster change (LCC) mechanism that only performs reclustering when multiple CH nodes become neighbors. In the vote-based clustering (VOTE) proposal [6], non-CH nodes join a CH only if the number of its cluster members is below a threshold, thus limiting the cluster size. Based on the knowledge of node location information, another approach [7] attempts to estimate the nodes relative mobilities and to capture the mobility patterns to form stable clusters. For the same purpose, the authors in [8] propose to build clusters using past, current and predicted nodes' positions through the help of a learning automaton. The clustering algorithm defined in [9] uses a Gauss-Markov model to calculate the velocity and direction of the nodes. The novelty of signal-attenuation aware clustering algorithm (SECA) [10] lies in the introduction of link qualities (based on received signal strength) combined with the nodes relative mobilities, to determine if a node becomes CH. Authors in [11] use centralized genetic algorithms and particle swarm optimization to select a stable CH. By contrast, only a few papers have tackled the problem of clustering structured networks. The authors in [12] introduce the type-based clustering algorithm (TCA). This clustering scheme associates a stability factor to each node and selects as CH the nodes that have the largest stability factor in a radio neighborhood. The stability factor takes group membership into account using the IP subnet of each node. A limitation of [4] TCA lies in the fact that two CH nodes cannot be neighbors. A

direct consequence in dense networks is the formation of large clusters. A second example is detailed in [13] which proposes a topology management mechanism for hierarchical group oriented networks, where groups are based on geographical locations. In [14] we have proposed the so-called distributed clustering based on operational group algorithm. This algorithm forms size limited clusters whose membership is close to the groups, and thus outperforms other clustering algorithms from the literature

II. PROPOSED WORK

The proposed framework will be practical for sustaining various mobile applications based on distributed cooperative packet delivery.

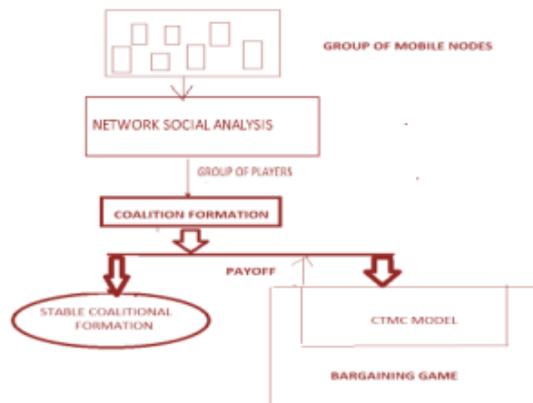


Fig.1. Block Diagram

Fig.1. Diagram showing the interrelationship among the three steps, namely, mobile node using NSA, bargaining model game, and coalitional game. The proposed method consists of three interconnected steps as shown in Fig. 2. We initially use a NSA-based approach [8], [9], [10] to be familiar with which mobile nodes have the potential to aid other mobile nodes for data delivery in the similar group. After the NSA-based mobile node grouping is finished, the mobile nodes in each group cooperate a coalitional game to obtain a constant coalitional structure. The payoff of every mobile node is a function of cost incurred by the mobile node in communicating packets and the release wait for packets spreaded to this mobile node from a BS. A continuous-time Markov chain (CTMC) model [1] is originated to attain the expected cost and packet

delivery delay for each mobile node in the similar coalition. Since the expected cost and packet delivery delay vary with the probability that each mobile node helps other mobile nodes deliver packets, a bargaining model game [11], is used to find the best helping probabilities for all the mobile nodes. For every mobile node, after the optimal probability of helping other mobile nodes is obtained, we can find out the payoff of every mobile node when it is a member of its current coalition. It obtained from this game are used to determine the solution of the coalitional game in terms of stable coalitional structure. A distributed algorithm is used to attain the solution of the coalitional game and a Markov chain-based analysis is presented to evaluate the stable coalitional structures obtained from the distributed algorithm. We suppose that the packets are not instantly discarded from the cache of the BSs or the mobile nodes after they are thrown or promoted. In addition, there is a controller at the submission server which gathers mobility information of the nodes by using the subsequent method:

- When the mobile nodes meet each other, they make a proof of the time they meet.
- Given a definite time period (e.g., 1 hour), the mobile nodes compute the meet rate with other nodes by separating the number of meet by the length of the time period.
- The mobile nodes provide the meet rate in sequence to the controller at the submission server irregularly.
- The controller maintains a record of the meet rate information for all the mobile nodes in the network, and this record is used for network social analysis (NSA). Also, the controller manages the information swap among the base stations or access points.

III. SIMULATION RESULTS

In this section, we present a process for mobile node grouping based on social network investigation. The main difficulty of coalition structure is that the computational complexity increases exponentially when the number of nodes increases [5], [12]. That's why, the most important purpose of the anticipated NSA-based mobile node grouping is to decrease the complexity of coalition structure when there are

various mobile nodes participating in the supportive information delivery scheme. The key method of the NSA-based mobile node grouping is to sort out several mobile nodes which will not give to the supportive packet delivery (i.e., to split the mobile nodes into multiple social groups in which mobile nodes in a social group do not help with the mobile nodes in another social group). A social network or a group is collected of nodes and ties. In this representation, every mobile node is a node and interaction of mobile nodes are ties. Whether or not a tie will be recognized between two nodes can be resolved by using centrality metrics used in graph hypothesis and network investigation. Centrality is a quantification of the relative consequence of a highest point within the graph (e.g., how important a node is within a social group). We recognize how every node is important to others based on the Poisson modeling of the network which is called Poisson process based centrality. To recognize groups of mobile nodes using their Poisson process-based centrality, we suggest an algorithm which ensures that for each mobile node in the same group, the possibility that the packet delivery postponement residues below a necessary time interval, can be maintained above a end threshold. Many mobile nodes can assist and appearance coalitions. We presume that every mobile node in the equal coalition will bring and onward packets to other mobile nodes when they gather each other. Each mobile node $k \in IN = \{1 \dots N\}$ has a communication range of g_k meters. We believe that over a period of time (e.g., 1 hour), we can expect the mobility and inter-encounter time pattern of every mobile node. Due to the property of speed and density of mobile nodes, the meet-associated statistical data may differ [21]. In such a case, the mobility and inter-encounter time pattern of mobile nodes composed through a small time period can be uttered as temporary social make contact with pattern which can be more useful than the increasing contact pattern to recover bring-and-onward-based data delivery [22]. Let mobile node k meet another mobile node i on the path with rate $r_{ki} = r_{ik}$ per unit of point in time and the number of encounters between mobile node k and mobile node i during a period of time is $n_{ki} = n_{ik}$. Let r_{k0} and r_{0k} be the rates that mobile node k assembles the base station and vice

versa. Note that "0" is used as the index of any base station and its transmission range is g_0 . The encounter method for every couple of nodes is implicit to pursue a Poisson process and the encounter rate is used as the matching constraint. For the encounter process, that the stochastic properties can be characterized by the Poisson hypothesis, was acceptable in [23], [24]. It was given away that the encounters between a couple of mobile nodes pursue a Poisson distribution if the nodes move in a narrow region. every mobile node k is preparing to help other mobile nodes to deliver packets with probability p_k (i.e., $p_k = 1$ if mobile node i always receives information packets, bring, and forwards them to other mobile nodes). Any mobile node k receives packet(s) from a BS or from other mobile node i in the similar coalition at the cost of c_{ki}^f per packet. Mobile node k then forwards the packet(s) to its destination or to another mobile node i' in the similar coalition at the cost of c_{ki}^f per packet. We suppose that every mobile node is capable to identify whether the other mobile nodes have the similar packet(s)

Algorithm 1 under recognizes the collection of mobile nodes.

The nodes in such a collection are the players in the bargaining model game and the coalitional game. In this algorithm, IN denotes the location of all mobile nodes and X_K is a vector denoting the relationship of mobile node k with other mobile nodes.

Algorithm 1. NSA-based mobile node grouping algorithm.

- 1: Exchange profile information (i.e., encounter information) among mobile nodes. Set $S = \emptyset$ a temporary variable.
- 2: Initialize locate of associations for all mobile nodes, i.e., $X_K = \emptyset, k \in IN$
- 3: for each mobile node $k \in IN = \{1 \dots N\}$
- 4: $S = S \cup \{k\}$
- 5: for each mobile node $i \in IN \setminus S$
- 6: if $(P_{ki}(T_{0k} + T_{ki} < T_i) \geq w_k$ and $P_{ik}(T_{0k} + T_{ki} < T_i) \geq w_i$ and $n_{ki} > n_{th}$)
- 7: Add mobile node i to mobile node k 's set of relationships and vice versa
- 8: $S_k = S_k \cup \{i\}$
- 9: $S_i = S_i \cup \{k\}$
- 10: end

- 11: end
12: end
13: Use the sets of relationships X_k of all the mobile nodes to build a graph $G(A,I)$
14: Set the vertices of the graph $A=IN$ (i.e., vertices are the mobile nodes)
15: Set the edges of the graph $I = \cup_{k=1}^N X_k$ (i.e., edges are the mobile nodes' relationships)
16: Identify each group k of mobile nodes, IM_j where $\cup IM_j = IN$, which is a maximal complete clique or subgraph in the graph $G(A,I)$ obtained by using algorithms such as those in [20].

IV. CONCLUSION

We have provided a coalitional game framework for bring-and-ahead-based cooperative packet delivery to cellular nodes in a community. The mobile nodes are coherent to form coalitions to maximise their individual payoffs. First, a continuous-time Markov chain version has been evolved to obtain the packet delivery put off and the predicted value of cell nodes for cooperative packet delivery. The packet delivery wait and the predictable fee rely on the opportunity that each mobile node will assist other mobile nodes inside the same coalition. Then, a bargaining model game has been formulated to locate the finest supporting possibilities for all the mobile nodes. Based on the packet delivery put off and expected value, a coalitional recreation has been formulated to model the selection making the technique of mobile nodes, that is, whether or not they will cooperatively deliver packets to different mobile nodes or no longer. A solid coalitional shape (i.e., set of coalitions) has been considered as the answer of this coalitional sport. Using the coalitional game version, the performance of cooperative packet shipping has been analyzed in terms of common packet delivery delay.

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